## Exam for CS-E3210 - Machine Learning: Basic Principles (27.10.2016) General Information

- Put your name and student id on EVERY page you use.
- To pass the course you must also pass the term project. Results of this examination are valid for one year after the examination date.
- Allowed equipment: calculator, pen, pencil and eraser.
- The number of points achieved for a question with M answer choices, when selecting T correct answers and F wrong answers is given by  $\max\{0, 10(T-F)/M\}$ .

Question 1. Consider a classification problem with three classes  $\mathcal{Y} = \{C_1, C_2, C_3\}$ . We observe a new point  $\mathbf{x} \in \mathcal{X}$  whose likelihood under the three classes is  $p(\mathbf{x}|r=C_1)=0.01$ ,  $p(\mathbf{x}|r=C_2)=0.40$  and  $p(\mathbf{x}|r=C_3)=0.60$ , respectively. Assume we have prior information that  $p(r=C_1)=0.98$  and  $p(r=C_3)=0.01$ . According to Bayesian decision theory we should classify  $\mathbf{x}$  as

	$r = C_3$ since it was most likely to be generated from that class.	$\bigcirc$
В.	$r=C_1$ since it yields highest posterior $\frac{p(\mathbf{x} r=C_1)p(r=C_1)}{p(\mathbf{x})}\approx 1/2$ .	$\bigcirc$
C.	$r = C_1$ since it yields highest product $p(\mathbf{x} r = C_1)p(r = C_1) \approx 1/100$ .	$\bigcirc$
D.	'reject' since no class $C$ gives $p(r = C \mathbf{x}) > 3/4$ .	$\bigcirc$
E.	None of the other answers is correct.	$\circ$

Question 2. Consider a regression problem with scalar input  $x \in \mathbb{R}$  and real-valued output  $r \in \mathbb{R}$ . Using polynomial basis functions  $\phi_i(x) = x^i$  for linear regression  $g(x) = x^i$  $\sum_{i=0}^{\hat{M}} w_i \phi_i(x)$ 

Α.	involves $M+1$ non-negative parameters $w_i \geq 0, i=0,\ldots,M$ .	$\bigcirc$
В.	gives a linear model $g(x) = w_0 + w_1 x$ if $M = 1$ .	$\bigcirc$
C.	results in a non-linear predictor if $M \geq 2$ .	$\bigcirc$
D.	in general tends to overfit with high $M$ .	$\bigcirc$
Ε.	none of the above is correct.	$\bigcirc$

Question 3. A popular method for choosing model complexity is cross-validation (CV), where the dataset  $\mathcal{D}$  is split into training, validation and test datasets. Following statements are true:

A.	We should always use 30% of data as test data.	$\bigcirc$
В.	Training and validation sets should be disjoint.	$\bigcirc$
C.	The error on the test set is an unbiased estimate for the generalisation error.	$\bigcirc$
D.	The model complexity should be selected using the error on the validation set.	$\bigcirc$
Ε.	In general, Leave-One-Out CV tends to overfit.	$\bigcirc$
F.	After selecting the model complexity, we can use training and validation sets to le	earn

the model parameters.

<b>Question 4.</b> Bias-variance decomposition (BVD) refers to the identity $\mathbb{E}_{\mathcal{D}}[(g_{\mathcal{D}}(x))^2] = \mathbb{E}_{\mathcal{D}}[(g_{\mathcal{D}}(x) - \mathbb{E}_{\mathcal{D}}g_{\mathcal{D}}(x))^2] + (\mathbb{E}_{\mathcal{D}}g_{\mathcal{D}}(x) - f(x))^2$ where $g_{\mathcal{D}}(x)$ is a regress mated from a dataset $\mathcal{D}$ , and $f(x)$ is the assumed true function. Following states are true:	sor esti-	
<ul> <li>A. BVD shows how stable a model is with respect to noise in the dataset.</li> <li>B. BVD shows how stable a model is with respect to the model complexity.</li> <li>C. More complex models typically yield high bias.</li> <li>D. More complex models typically yield high variance.</li> <li>E. A model which yields low bias tends to overfit the data.</li> <li>F. A model yielding low bias typically incurs high variance, and vice versa.</li> <li>G. Adding a zero-mean prior or regulariser increases bias.</li> <li>H. There always exist models yielding zero bias and zero variance.</li> <li>I. More complex models tend to have higher bias.</li> <li>J. Decreasing bias is always preferred to decreasing variance.</li> <li>K. None of the other answers is correct.</li> </ul>	00000000000	
Question 5. In Bayesian learning, we learn a posterior distribution $p(\theta \mathcal{D})$ of the pareters $\theta$ given the data $\mathcal{D}$ . The predictive distribution $p(r x,\mathcal{D})$ describes the distribution an estimated response $r$ for a new input $x$ given the data $\mathcal{D}$ . The ideal Bayesian is dictive distribution uses		
A. the most likely parameter values $\theta_{\text{ML}} = \operatorname{argmax}_{\theta} p(\mathcal{D} \theta)$ as $p(r x, \theta_{\text{ML}})$ . B. the highest posterior value $\theta_{\text{MAP}} = \operatorname{argmax}_{\theta} p(\theta \mathcal{D})$ as $p(r x, \theta_{\text{MAP}})$ . C. the expected likelihood value $\theta_{\text{Bayes}} = \int \theta p(\mathcal{D} \theta) d\theta$ as $p(r x, \theta_{\text{Bayes}})$ . D. the expected posterior value $\theta_{\text{Bayes}} = \int \theta p(\theta \mathcal{D}) d\theta$ as $p(r x, \theta_{\text{Bayes}})$ . E. expectation over the posterior, i.e., $p(r x, \mathcal{D}) = \int p(r x, \theta) p(\theta \mathcal{D}) d\theta$ . F. expectation over the likelihood, i.e., $p(r x, \mathcal{D}) = \int p(r x, \theta) p(\mathcal{D} \theta) d\theta$ . G. None of the other answers is correct.	000000	
Question 6. Let $\mathcal{I}("statement")$ denote the indicator function which is equal "statement" is true and equal to zero else. We call a classifier $h(\cdot): \mathbb{R}^2 \to \{0,1\}$	to one if linear if	
A. its decision boundary is a line. B. its decision boundary is a circle. C. it can be written as $h(\mathbf{x}) = \mathcal{I}(\mathbf{w}^T\mathbf{x} \geq w_0)$ for some $\mathbf{w} \in \mathbb{R}^2, w_0 \in \mathbb{R}$ . D. it can be written as $h(\mathbf{x}) = \mathcal{I}(x_1^2 + x_2^4 \geq 0)$ . E. None of the other answers is correct.	00000	
Question 7. The technique called "Bagging"		
<ul> <li>A. combines the predictions obtained for different (but related) datasets.</li> <li>B. puts more emphasis on training examples which are predicted incorrectly.</li> <li>C. only amounts to resampling the dataset.</li> <li>D. None of the other answers is correct.</li> </ul>	0000	

Question 8. We observe labeled data $\mathcal{D} = \{\mathbf{x}^t, r^t\}_{t=1}^N$ which we stack into the vertex $\mathbf{r} = (r^1, \dots, r^N) \in \mathbb{R}^N$ and matrix $\mathbf{X} = (\mathbf{x}^1, \dots, \mathbf{x}^N)^T \in \mathbb{R}^{N \times d}$ , respectively. The control of the real-valued output/label $r^t$ from the multivariate in $\mathbf{x}^t \in \mathbb{R}^d$ under squared error loss $E(g(\cdot) \mathcal{D}) := (1/N) \sum_{t=1}^N (r^t - g(\mathbf{x}^t))^2$ .  A. is always given by $g(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$ with weight vector $\mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{r}$ .  B. is always unique, i.e., there is one and only one optimal predictor $g(\mathbf{x})$ .  C. can be found by gradient descent for the cost function $E(g(\cdot) \mathcal{D})$ .  D. does not exist for some datasets.  E. None of the other answers is correct.	etor pti- put
<ul> <li>Question 9. The "Bootstrap" method</li> <li>A. is a parametric machine learning method.</li> <li>B. is a classification method.</li> <li>C. allows to assess the reliability of a hypothesis.</li> <li>D. can only be used for unlabeled data.</li> <li>E. can be used for "Bagging".</li> <li>F. None of the other answers is correct.</li> </ul>	00000