- 1. Are the following claims true (**T**) or false (**F**)? Every correct answer gives you +1 p, every incorrect -1 p, and an empty answer is worth 0 p. The minimum amount of total points is 0 p and maximum 6 p.
  - a) A real-time system must satisfy bounded response-time constraints or risk severe consequences, including failure. **T** (p. 5 of the textbook)
  - b) A firm real-time system is one in which performance is degraded but not destroyed by failure to meet response-time constraints. **F** (p. 7 of the textbook)
  - c) A typical power-loss alarm belongs to the class of sporadic and asynchronous events. T (p. 10 of the textbook)
  - d) Extensive instruction pipelining helps in making a real-time system deterministic. **F** (p. 46 of the textbook)
  - e) There are industrial modifications of the Ethernet network, and thus the borderline between office and fieldbus networks is becoming blurred. T (p. 69 of the textbook)
  - f) Energy-aware operating systems are used in wireless sensor network applications. T (p. 141 of the textbook)
- 2. An individual elevator controller in a bank of multiple elevators has the following periodical tasks with execution periods of  $p_i$  and worst-case execution times of  $e_i$  {i = 1,2,3,4}:

Task 1: Communicate with the group dispatcher;  $p_1 = 500 \text{ ms}$ ,  $e_1 = 12 \text{ ms}$ . Task 2: Update the car position information and manage runs/door;  $p_2 = 25 \text{ ms}$ ,  $e_2 = 5 \text{ ms}$ . Task 3: Register and cancel car calls;  $p_3 = 75 \text{ ms}$ ,  $e_3 = 1 \text{ ms}$ . Task 4: System supervisions and self-diagnostics;  $p_4 = 200 \text{ ms}$ ,  $e_4 = 32 \text{ ms}$ .

What is the overall CPU utilization factor in this case? (6 p) (similar example on p. 13 of the textbook)

3. You have a 12-bit A/D converter and its input range is –12V to +12V.

If the analog input to the A/D is -4.3V what is the corresponding digital output in binary format? (6 p) (similar example on p. 87 of the slides of Chapter 2)

- 4. The priority inversion problem is related to real-time operating systems under certain operating conditions.
  - a) Explain such a condition with an illustrative example. (3 p)
  - b) Why is the condition undesirable? (1 p)
  - c) How could the priority inversion problem be prevented in your example case? (2 p) (example on pp. 118– 120 of the textbook)
- 5. Consider a real-time kernel with preemptive-priority scheduling.
  - a) Draw a state diagram that shows all the possible task states and allowed transitions between them. (4 p)
  - b) Define the states and transitions. (2 p) (pp. 95–97 of the textbook)