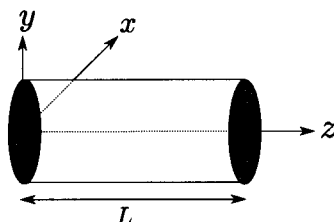


1. Explain shortly the concepts:
 - (a) Dynamic viscosity
 - (b) Bulk viscosity
 - (c) Laminar flow
 - (d) Young's modulus
 - (e) Elastic wave
 - (f) Yield stress
2. Explain the main concepts of modeling a flowing fluid.
3. A fluid flows in a long pipe with a circular cross section of radius a . Assume that the flow is stationary and incompressible and that there is no volumetric forces present. The pressure at $z = 0$ is p_1 and at $z = L$ the pressure is p_2 . The density of the fluid is ρ and the kinematic viscosity ν .



- (a) Solve for the pressure field p and the velocity field \mathbf{v} of the fluid.
 - (b) Calculate the drag force the fluid exerts on the wall of the cylinder for $0 \leq z \leq L$.
 - (c) Calculate the mass flow rate through the pipe.
4. Give an example of a strain tensor for which there is
 - (a) an increase in volume.
 - (b) extension in the z -direction, but overall decrease in volume.
 - (c) shear strain, but no volume change.

For the strain tensor of (a) write down the corresponding stress tensor for an isotropic solid given the Lamé coefficients μ and λ .¹

5. A two-dimensional problem of a rectangular bar stretched by uniform end loadings results in the following constant strain field:

$$\epsilon = \begin{bmatrix} C_1 & 0 & 0 \\ 0 & -C_2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

where C_1 and C_2 are constants. Assuming the field depends only on x and y , integrate the strain-displacement relations to determine the displacement components and identify any translation and rotation terms.

Equations

- Euler's equation:

$$\frac{\partial}{\partial t} \vec{v} + (\vec{v} \cdot \nabla) \vec{v} = -\frac{1}{\rho} \nabla p + \vec{f}$$

- Mass continuity:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

- Navier-Stokes equation:

$$\frac{\partial}{\partial t} \vec{v} + (\vec{v} \cdot \nabla) \vec{v} = \vec{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \vec{v} + \frac{1}{\rho} \left(\zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \vec{v})$$

- Vector identities:

$$(\vec{v} \cdot \nabla) \vec{v} \equiv (\nabla \cdot \vec{v}) \vec{v} - \vec{v} (\nabla \cdot \vec{v})$$

$$(\vec{v} \cdot \nabla) \vec{v} \equiv \nabla \left(\frac{1}{2} v^2 \right) - [\vec{v} \times (\nabla \times \vec{v})]$$

- Strain:

$$\epsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

- Strain for a Hookean material

$$\epsilon_{ij} = -\frac{1}{9K} \delta_{ij} \text{Tr}(T) - \frac{1}{2\mu} \left(T_{ij} - \frac{1}{3} \delta_{ij} \text{Tr}(T) \right)$$

- Stress for a Hookean material

$$T_{ij} = -K \delta_{ij} \text{Tr}(\epsilon) - 2\mu \left(\epsilon_{ij} - \frac{1}{3} \delta_{ij} \text{Tr}(\epsilon) \right)$$

$$T_{ij} = -\lambda \delta_{ij} (\nabla \cdot \vec{u}) - \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$