Be concise and clear. The shorter you can be the better. The simplicity of the solutions and answers is an important grading criterion! NOTE: There are only 4 questions in this exam!

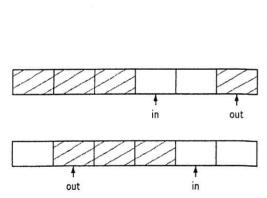
 Prove with proper invariants that the following simple two-process version of the bakery algorithm for the critical section is safe.

	Algorithm 5.1: Bake	ry algorith	nm (two processes)	
integer np ← 0, nq ← 0				
р			q	
loop forever			loop forever	
p1:	non-critical section	q1:	non-critical section	
p2:	$np \leftarrow nq + 1$	q2:	$nq \leftarrow np + 1$	
p3:	await $nq = 0$ or $np \le nq$	q3:	await $np = 0$ or $nq < np$	
p4:	critical section	q4:	critical section	
p5:	np ← 0	q5:	nq ← 0	

Does it satisfy the necessary liveliness requirements? Prove this with temporal logic or disprove with a contradicting example.

Analyze the atomicity of its statements. Are they minimal to achieve safety, or could they be broken to smaller ones?

2. A bounded buffer is frequently implemented as a circular buffer, which is an array indexed modulo its length. The index variable in points to the next empty space for a producer and out the next full for a consumer (see the picture below on the left). Prove with proper invariants that the following algorithm, where synchronization between a producer and a consumer is solved with semaphores works correctly.



Algorithm 6.19: Prod	lucer-consumer (circular buffer)		
dataType array [0N] buffer			
integer in, out ← 0			
semaphore	$notEmpty \leftarrow (0, \emptyset)$		
semaphore	$notFull \leftarrow (N, \emptyset)$		
producer	consumer		
dataType d	data Type d		
loop forever	loop forever		
p1: d ← produce	q1: wait(notEmpty)		
p2: wait(notFull)	q2: d ← buffer[out]		
p3: buffer[in] ← d	q3: out ← (out+1) modulo N		
p4: in $\leftarrow$ (in+1) modulo N	q4: signal(notFull)		
p5: signal(notEmpty)	q5: consume(d)		

Analyze the situation if several producers and consumers access the buffer at the same time. Is it still correct or should it be enhanced and how?

- 3. One-lane bridge. Cars coming form north and south have to cross a very long and narrow one-lane bridge. Cars driving to the same direction maybe on the bridge at the same time, but cars heading to opposite directions are not allowed. Consider the following Java code outline for the solution to the problem, where the cars are threads calling the public methods cross\_from\_North() and cross\_from\_South() of the class One\_lane\_bridge. Complete the missing peaces of the synchronization logic using Java. Do not worry about the performance or fairness first, however the directions should be treated symmetrically. Be clear when defining the needed variables! Write down two invariants specifying:
  - 1) There can be several cars on the bridge at the same time, but they must all head to the same direction.
  - 2) There is no unnessary waiting. Give an argument that both of them they are preserved.

Analyze the performance of your solution and suggest potential improvements to it. Analyze the fairness of your solution and suggest potential improvements to it.

4. Tuple Space. Write a tuple-space solution to the one-lane bridge problem. Define clearly the meaning of the different tuple types used and attach appropriate tags to them. No global variables except tuples should be used. The simpler your solution is, the better. Discuss the pros and cons of your solution. Use tuple-space operations: postnote ('tag', ...), readnote ('tag', ...), removenote ('tag', ...). Indicate clearly in a readnote (...), or removenote (...) operation when a matching tuple containing element equal to the value of a program variable v value is sought for with syntax "v=" from the case where an element value of an otherwise matching tuple is just assigned to a program variable (syntax "v").

Analyze the fairness of your solution and suggest potential improvements to it.